

Specification

Article-No.	XXXXX	Index	00
Printed	12.03.12	Page	1
		of	3

No.	Property	Nominal Value	Test Method
1	<b>Component(s)</b> Type of Component	Fan Motor for Air Cleaner H600 Serie Electrical commutated Motor with low voltage and internal Rotor	

2	General		
2.1	Material	All used materials according to Directive 2011/65/EU (RoHS).	
2.2	Yearly Quantity	10'000 pcs	
2.3	Purchasing Price	approx. EUR 20,	

3	Electrical Requirements		
3.1	Supply Voltage	24VDC – 48VDC	
	Supply Quality	External Switching Power Supply	
3.2	Power Consumption		
	At min. Load	5W – 10W	
	At max. Load	70W	
3.3	Speed		
	Min.	200 – 500 min <sup>-1</sup>	To be defined
	Max.	1400 – 2100 min <sup>-1</sup>	To be defined
3.4	Efficiency	Min. 82%,	
		Target > 88%	
3.5	Torque		
	At 25W	0.11 – 0.19 Nm	To be defined
	At 70W	0.27 – 0.41 Nm	To be defined

4	Noise Requirements		
4.1	A single sound noise (often at block commutated motors) is not acceptable.		
4.2	Noise Level @ 500 min <sup>-1</sup>	< 22dB(A)	Measured on soft ground and
	Noise Level @ 800 min <sup>-1</sup>	< 30dB(A)	1m distance of motor.
	Noise Level @ max.	< 38dB(A)	
	Acceptable Noise Level Rise until life time expectancy	Max. +6dB(A)	

5	Commutation Type		
5.1	Because of the noise requirements a sinus-commutated solution is necessary. Duty cycle min. 20kHz (also for babies not audible).		
6	Mechanical Layout		
6.1	The motor must be enclosed wi	th a waterproof housing (see protection cla	iss).
	To reach the target noise level PLASTON AG recommend to use a motor with two bearings with long distance to each other. The durability of the bearing must be verified with > 35'000 hours.		
	Active force quality of the load (Plastic Fan with 220mm diameter) <20mm/s (for identification of the radial load for the verified durability of the bearing). Active force quality of the rotor <5mm/s according to ISO 1940.		
6.2	Fixation of motor housing	Elastomer coupling without any	



## Specification

Article-No.	XXXXX	Index	00
Printed	12.03.12	Page	2
		of	3

		mechanical fixation to the unit itself.	
6.3	Mounting position	Axis horizontal	
6.4	Active force quality of the load	< 20 mm/s	Plastic fan with ø 220mm
6.5	Active force quality of the rotor	< 5 mm/s	ISO 1940
6.6	Shaft end	To be defined.	

7	Overall Size		
7.1	Diameter	Max. 110 mm	
	Length/Thickness	Max. 80 mm	
	Protection Class	IP43	
	Climate Requirements	-20℃ to 70℃,	A CONTRACTOR OF A CONTRACTOR OFTA CONTRACTOR O
		10% rel. Humidity to 95% rel. Humidity	
	Typ. Working Condition	23℃ with 85% rel. Humidity	
	Typ. Storage Condition	-10℃/40℃ with 95% rel. Humidity	
	Life time corrosion protection	10 years without any loss of functionality	
7.2	Connection Wire Length	Ca. 300 mm	
7.3	Wire	To be defined.	
7.4	Board Connector	To be defined.	

8	Air Ventilation / Cooling		
8.1	The motor parts (Stator and Rotor) are embedded in an enclosed elastomer coupling which is almost air- proof. The fixation and heat transmission is guarnteed with the form-fit plastic housing which is located in an air-flow caused by the rotating plastic fan. So the cooling is only defined over the heat transmission and the air-flow of the fan.		
8.2	Convection	Inside the motor housing	
8.3	Maximum Temperature of motor plastic housing	120°C	
8.4	Insulation Class:	B to F	

Control		
Control		
The motor control is integrated	in the motor housing, e.g. Printed Circuit E	Board inside the motor housing
EMC-Compatibility	Considered in the motor control	
Speed Control	<ul> <li>PWM (Pulse-Width Modulation)</li> <li>or Voltage Signal 0 – 5VDC</li> <li>or Frequency Signal</li> </ul>	
Feedback Motor	<ul> <li>Error indication</li> <li>Actual Speed (Frequency Signal)</li> </ul>	
The individual placement of different filter mats and the changeable back pressure (depends of more or less polluted filter mat) causes different load characeristics. This fact should have no influence on the maximum power point (to be defined). At other selected power steps the speed need to be constant as well (no power control).		
	Control The motor control is integrated EMC-Compatibility Speed Control Feedback Motor The individual placement of diff less polluted filter mat) causes maximum power point (to be de At other selected power steps t	Control         The motor control is integrated in the motor housing, e.g. Printed Circuit E         EMC-Compatibility       Considered in the motor control         Speed Control       - PWM (Pulse-Width Modulation)         - or Voltage Signal 0 – 5VDC       - or Frequency Signal         Feedback Motor       - Error indication         - Actual Speed (Frequency Signal)         The individual placement of different filter mats and the changeable back p         less polluted filter mat) causes different load characeristics. This fact shou maximum power point (to be defined).         At other selected power steps the speed need to be constant as well (no p

10	Bar code label	Code Type 128, foil-coated label ; dimension and position see fig. 1;	
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## Specification

Article-No.	XXXXX	Index	00
Printed	12.03.12	Page	3
		of	3

11	Approvals		
12	Durability	Min. 35'000 h	
13	Packaging		
14	Changes of specifications	Every change needs to be made in a written form.	
15	Other applicable documents	none	
16	Delivery		

## Issue

	Created	Approved	Filling
Distribution list	R&D	PUR	L/R&D
Date / Sign	05.03.2012 /UG/ OA		

## Changes

Ind.	Date	Vis.	Description of changes
01			
02			
03			